Company: _____

Address: _____

_____

Phone: _____ Fax: _____

Name: _____ Department: _____

E-mail: _____ Date: _____

Description of drive:

_____

_____

1. Mode of operation

Limitation of torque by:

- ☐ Slipping
- ☐ Ratching
- ☐ Idle rotation (load separating)
- ☐ Signalizing in case of overload without interrupting the torque transmission
- ☐ Signal in case of overload:
  Yes ☐ No ☐

Re-engagement:

- ☐ Automatic (DK)
- ☐ Automatically synchronous after 360° (SK)
- ☐ Manual (FR)

2. Backlash-free torque transmission

Yes ☐ No ☐

3. Arrangement as shaft coupling

Driving side:	Shaft diameter	_____	mm
	Length:	_____	mm
Driven side:	Shaft diameter	_____	mm
	Length:	_____	mm

4. Drive: E-motor

Starting torque T_{AS} _____ Nm or Tilting torque T_{AS} _____ Nm

Asynchronous ☐ Direct starting ☐ λΔ start ☐

Other: _____

5. Driving power and speed

Driving power: _____ kW

Speed of torque limiter: _____ rpm

- ☐ The overall driving power is transferred to the torque limiter
- ☐ Power: _____ to torque limiter

6. Driven side

Load torque required _____ Nm

Number of overload cases _____ per month

Rundown-time in case of overload _____ sec.

Release torque to be set _____ Nm
(The release torque must be minimum 30 % above the maximum operating torque.)

Setting records: Yes ☐ No ☐

7. Mounting conditions

☐ In a closed machine housing

☐ Open, in a closed space

☐ In oil tempering or oil dust

☐ Outdoor, ambient temperature
from _____ to _____ °C

☐ Other (accessibility, dust volume, etc.):
_____

☐ With an arrangement as a shaft coupling

Max. parallel displacement of coupling _____ mm

Max. angular displacement _____ Degree

Max. axial displacement _____ mm

Distance between shaft ends _____ mm

8. Anticipated demand

_____ Piece (once)

_____ Pieces/month

_____ Pieces/year

9. Documentations and specifications by QM

☐ Material test certificate: _____

☐ Initial sample test report: _____

☐ ATEX: ☐ Yes ☐ No _____

☐ Other: _____

10. Drive system with connecting dimensions required
